

Target specification

Toshiba Bi-CD Integrated Circuit Silicon Monolithic

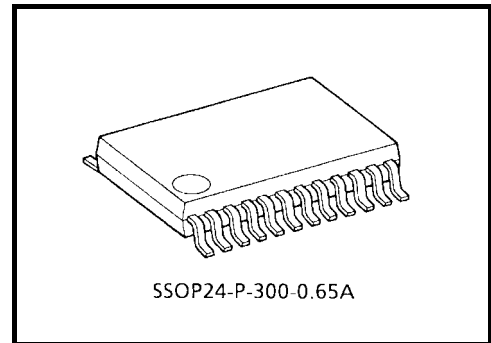
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Driver IC for Dual DC motor

TB6612FNG is a driver IC for DC motor with output transistor in LD MOS structure with low ON-resistor. Two input signals, IN1 and IN2, can choose one of four modes such as CW, CCW, short brake, and stop mode.

Features

- Power supply voltage ; $V_M=15V$ (Max.)
- Output current ; $I_{out}=1.2A(ave) / 3.2A$ (peak)
- Output low ON resistor ; 0.5 (upper + lower Typ. @VM 5V)
- Standby (Power save) system
- CW/CCW/short brake/stop function modes
- Built-in thermal shutdown circuit and low voltage detecting circuit
- Small faced package (SSOP24 : 0.65mm Lead pitch)
- Response to Pb free packaging



質量: 0.14 g (標準)

- * This product has a MOS structure and is sensitive to electrostatic discharge. When handling this product, ensure that the environment is protected against electrostatic discharge by using an earth strap, a conductive mat and an ionizer. Ensure also that the ambient temperature and relative humidity are maintained at reasonable levels.

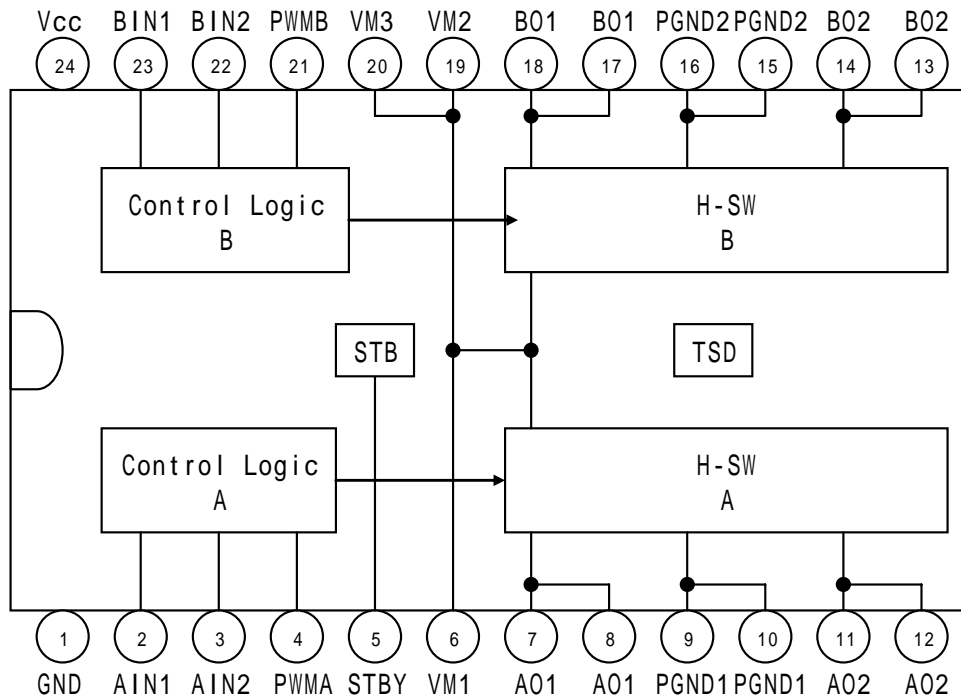
The TB6612FNG is a Pb-free product.
The following conditions apply to solderability:

*Solderability

1. Use of Sn-37Pb solder bath
 - *solder bath temperature = 230°C
 - *dipping time = 5 seconds
 - *number of times = once
 - *use of R-type flux
2. Use of Sn-3.0Ag-0.5Cu solder bath
 - *solder bath temperature = 245°C
 - *dipping time = 5 seconds

Block Diagram

Pin layout is unspecified at the date of Feb.7 in 2006.



Pin Functions

Pin NO.	Symbol	Characteristics	Remarks
1	GND	—	Small signal GND
2	AIN1	I	chA input 1 / 200kΩ pull-down at internal
3	AIN2	I	chA input 2 / 200kΩ pull-down at internal
4	PWMA	I	chA PWM input / 200kΩ pull-down at internal
5	STBY	I	" L " =standby / 200kΩ pull-down at internal
6	VM1	—	Motor supply (2.5V~13.5V)
7	AO1	O	chA output 1
8	AO1	O	chA output 1
9	PGND1	—	Power GND
10	PGND1	—	Power GND
11	AO2	O	chA output 2
12	AO2	O	chA output 2
13	BO2	O	chB output 2
14	BO2	O	chB output 2
15	PGND2	—	Power GND
16	PGND2	—	Power GND
17	BO1	O	chB output 1
18	BO1	O	chB output 1
19	VM2	—	Motor supply (2.5V ~ 13.5V)
20	VM3	—	Motor supply (2.5V ~ 13.5V)
21	PWMB	I	chB PWM input / 200kΩ pull-down at internal
22	BIN2	I	chB input 2 / 200kΩ pull-down at internal
23	BIN1	I	chB input 1 / 200kΩ pull-down at internal
24	Vcc	—	Small signal supply

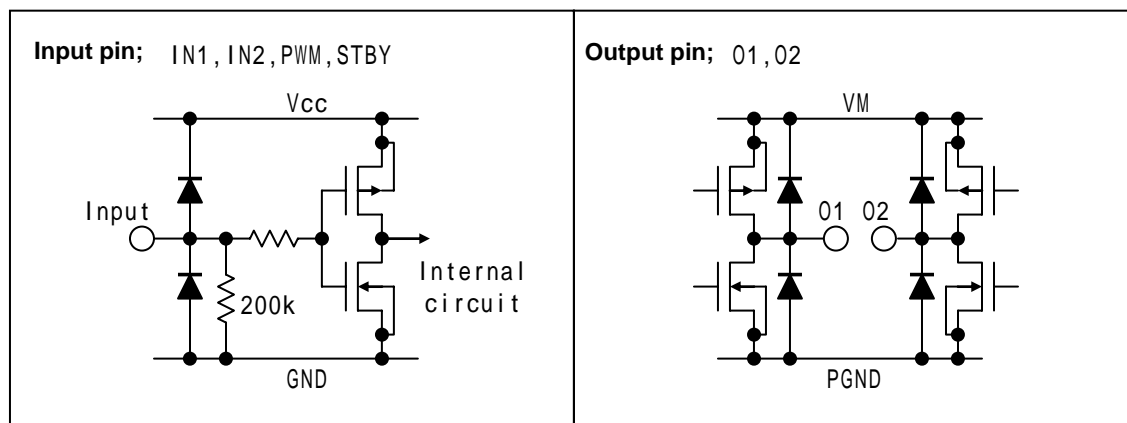
Maximum Ratings (Ta = 25°C)

Characteristics	Symbol	Rating	Unit	Remarks
Supply voltage	VM	15	V	
	Vcc	6		
Input voltage	VIN	-0.2 ~ 6	V	IN1,IN2,STBY,PWM pins
Output voltage	Vout	15	V	O1,O2 pins
Output current	Iout	1.2	A	tw=20ms Superimposed pulse per 1ch, Duty 30%
	Iout (peak)	2		
		3.2		
Power dissipation	PD	0.78	W	IC only
		0.89		Note 1
Operating temperature	Topr	-20 ~ 85		
Storage temperature	Tstg	-55 ~ 150		

Note1. 50x50x1.6mm When it is packaged to the board made of glass-epoxy (Cu40%).

Operating Range (Ta=-20 ~ 85)

Characteristics	Symbol	Min	Typ.	Max	Unit	Remarks
Supply voltage	Vcc	2.7	3	5.5	V	
	VM	2.5	5	13.5	V	
Output current (H-SW)	Iout	---	---	1.0	A	VM 5V
		---	---	0.4		5V > VM 2.5V
Switching frequency	fPWM	---	---	100	k H z	

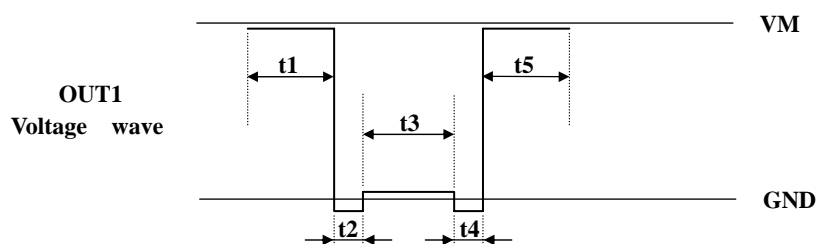
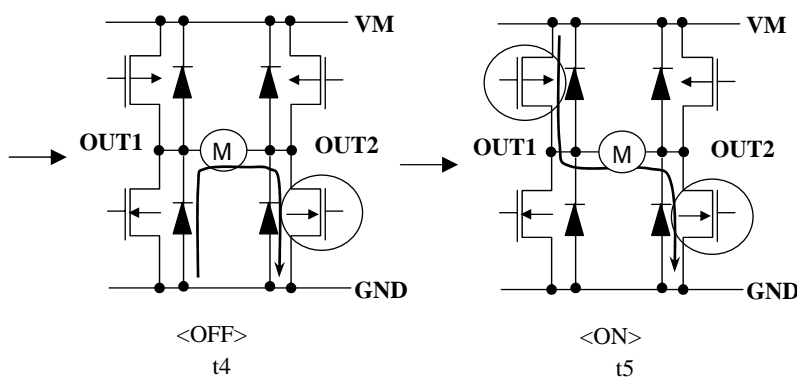
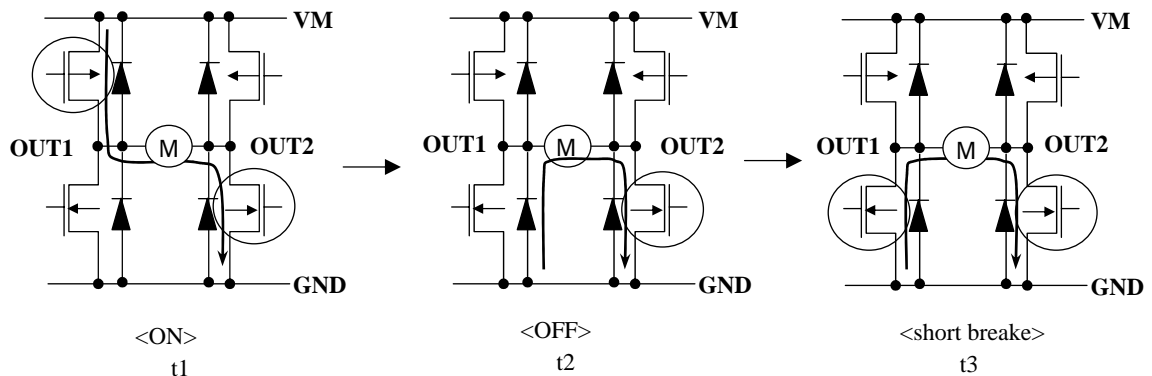


H-SW Control Function

Input				Output		
IN1	IN2	PWM	STBY	OUT1	OUT2	Mode
H	H	H	H	L	L	Short brake
L	H	H	H	L	H	CCW
		L	H	L	L	Short brake
H	L	H	H	H	L	CW
		L	H	L	L	Short brake
L	L	H	H	OFF (High impedance)		Stop
H / L	H / L	H / L	L	OFF (High impedance)		Standby

H-SW Operating Description

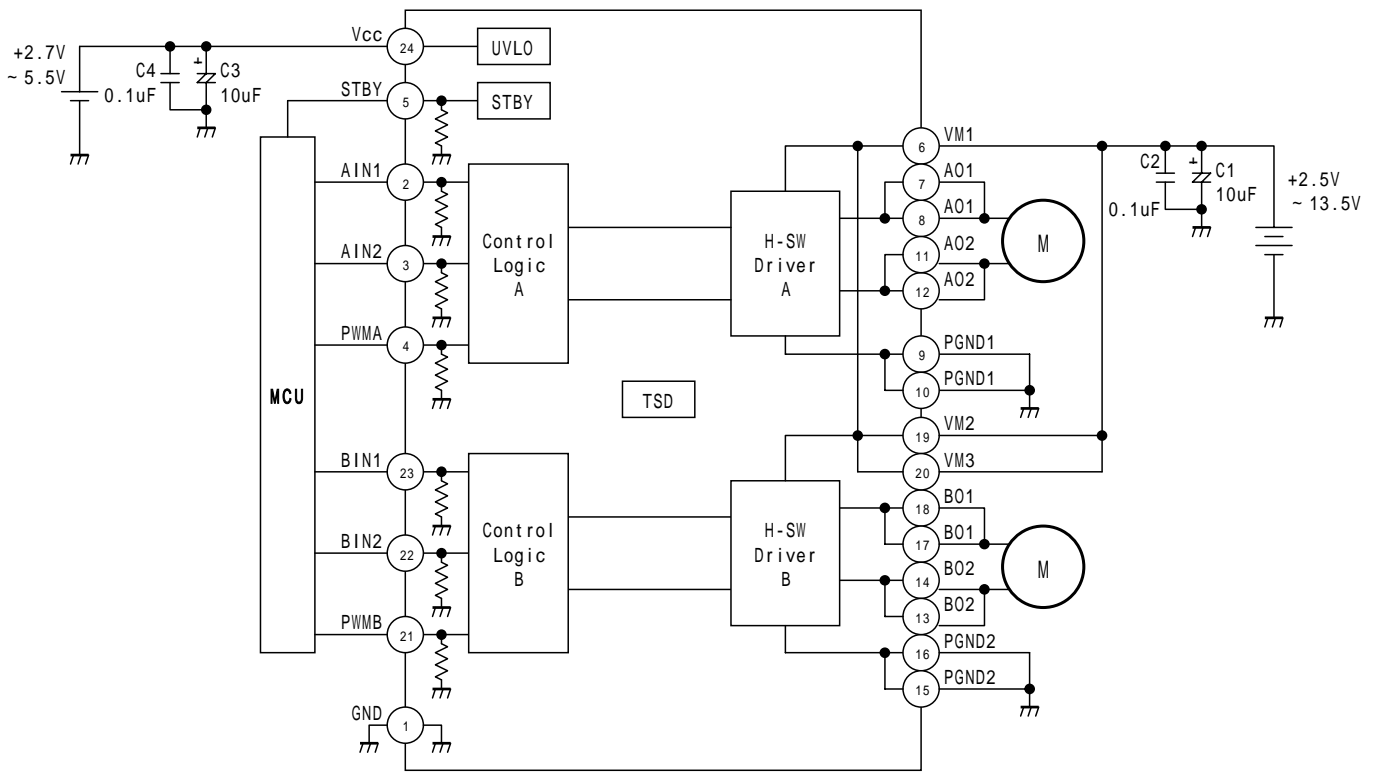
· To prevent penetrating current, dead time t_2 and t_4 (100ns : Designed value) is provided in switching to each mode in the IC.



Electrical Characteristics (unless otherwise specified, Ta = 25°C, V_{CC}=5V, VM=5V)

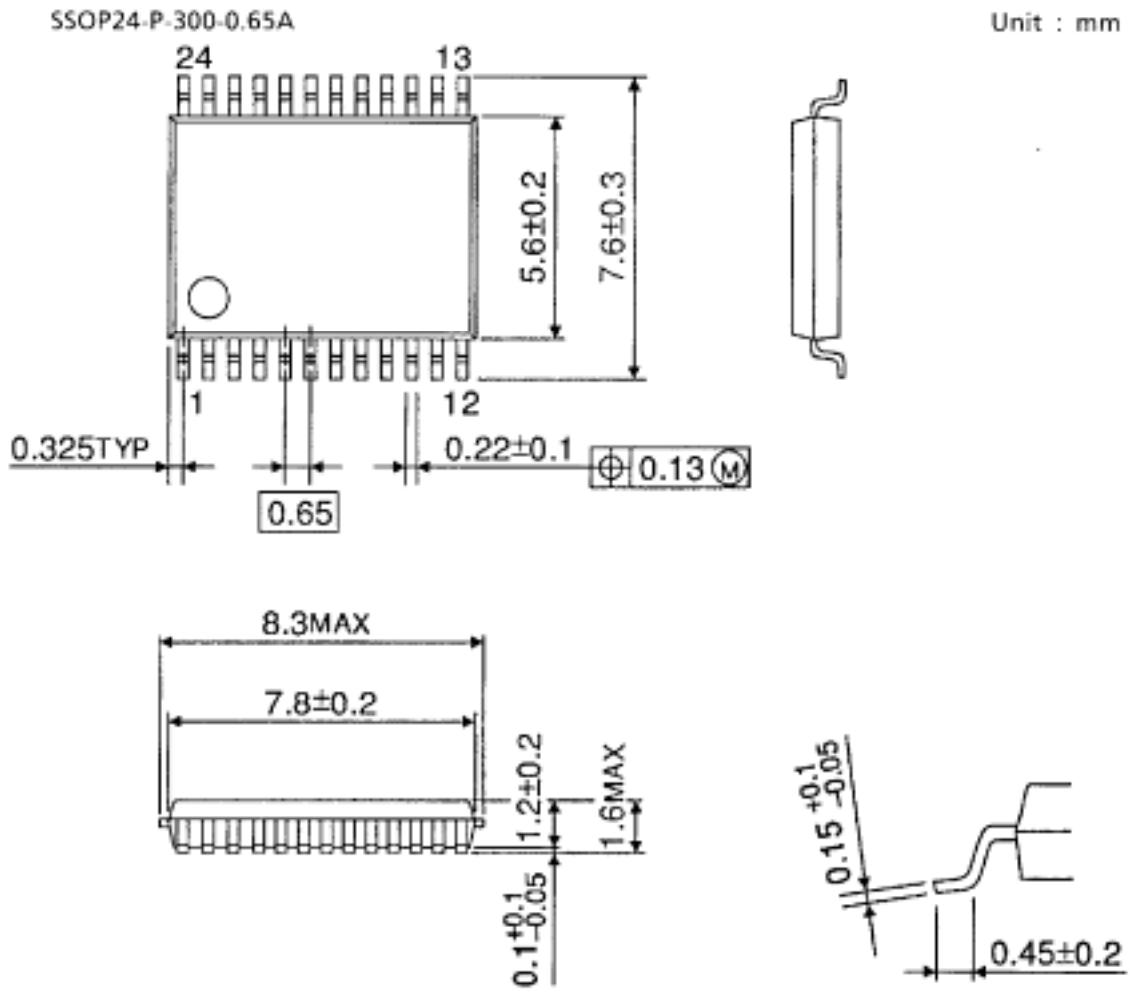
Characteristics	Symbol	Test Condition	Min	Typ.	Max	Unit
Supply current	I _{CC}	STBY=V _{CC}	---	0.9	1.2	mA
	I _{CC} (STB)	STBY=0V	---	---	1	μA
	I _M (STB)		---	---	1	
Control input voltage	V _{IH}		V _{CC} ×0.7	---	V _{CC} +0.2	V
	V _{IL}		-0.2	---	V _{CC} ×0.3	
Control input current	I _{IH}	V _{IN} =3V	5	15	25	μA
	I _{IL}	V _{IN} =0V	---	---	1	
Standby input voltage	V _{IH} (STB)		V _{CC} ×0.7	---	V _{CC} +0.2	V
	V _{IL} (STB)		-0.2	---	V _{CC} ×0.3	
Standby input current	I _{IH} (STB)	V _{IN} =3V	5	15	25	μA
	I _{IL} (STB)	V _{IN} =0V	---	---	1	
Output saturating voltage	V _{SAT} (U+L)1	I _O =1A, V _{CC} =V _M =5V	---	(0.5)	(0.7)	V
	V _{SAT} (U+L)2	I _O =0.3A, V _{CC} =V _M =3V	---	(0.24)	(0.34)	
Output leakage current	I _L (U)	V _M =V _{OUT} =15V	---	---	1	μA
	I _L (L)	V _M =15V, V _{OUT} =0V	-1	---	---	
Regenerative diode VF	V _F (U)	I _F =1A	---	1	1.1	V
	V _F (L)		---	1	1.1	
Low voltage detecting voltage	UVLD	(Designed value)	---	2.0	---	V
Recovering voltage	UVLC		---	2.2	---	
Response speed	t _r	(Designed value)	---	(10)	---	ns
	t _f		---	(100)	---	
	Dead time	Prevent from penetrating time(Designed value)	---	(100)	---	
Thermal shutdown circuit operating temperature	TSD	(Designed value)	---	(170)	---	
Thermal shutdown hysteresis	Δ TSD		---	(20)	---	

Typical Application Diagram



Note: The power supply capacitor should be connected as close as possible to the IC.

Package Dimennsions



Weght: 0.14 g (typ)

Notes on Contents

1. Block Diagrams

Some of the functional blocks, circuits, or constants in the block diagram may be omitted or simplified for explanatory purposes.

2. Equivalent Circuits

The equivalent circuit diagrams may be simplified or some parts of them may be omitted for explanatory purposes.

3. Timing Charts

Timing charts may be simplified for explanatory purposes.

4. Maximum Ratings

The absolute maximum ratings of a semiconductor device are a set of specified parameter values which must not be exceeded during operation, even for an instant.

If any of these ratings are exceeded during operation, the device electrical characteristics may be irreparably altered and the reliability and lifetime of the device can no longer be guaranteed.

Moreover, these operations with exceeded ratings may cause breakdown, damage and/or degradation to other equipment. Applications using the device should be designed so that each maximum rating will never be exceeded in any operating conditions.

Before using, creating and/or producing designs, refer to and comply with the precautions and conditions set forth in this document.

5. Application Circuits

The application circuits shown in this document are provided for reference purposes only. Thorough evaluation is required, especially at the mass production design stage.

Toshiba does not grant any license to any industrial property rights by providing these examples of application circuits.

6. Test Circuits

Components in the test circuits are used only to obtain and confirm the device characteristics. These components and circuits are not guaranteed to prevent malfunction or failure from occurring in the application equipment.

About the handling of ICs

Install the product correctly to avoid breakdown, damage and/or degradation to the product or equipment.

About overcurrent protection and heat protection circuits

These protection functions are intended to guard against certain output short circuits or other abnormal conditions with only temporary effect, and are not guaranteed to prevent the IC from being damaged.

- These protection features may not be effective if the product is operated outside the guaranteed operating ranges, and some output short circuits may result in the IC being damaged.

The overcurrent protection feature is only intended to protect the IC from a temporary short circuit.

Short circuits of longer duration may damage the IC through undue stress. The systems must be configured so that any overcurrent condition will be eliminated as soon as possible.

Counter-electromotive force

When the motor reverses or stops, counter-electromotive force in the motor may influence the current to flow to the power source. If the power source lacks sink capability, the IC power and output pins may exceed the rating. The counter-electromotive force of the motor varies depending on the conditions of use and the features of the motor.

Therefore ensure that there is no damage to the IC or problem in operation, and no error in or damage to peripheral circuits resulting from counter-electromotive force.

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